



Erratum

Erratum to “A novel technique for position analysis of planar compliant mechanisms” [Mech. Machine Theory 40 (2005)1224–1239]

S. Venanzi^a, P. Giesen^b, V. Parenti-Castelli^{a,*}

^a DIEM – Department of Mechanical Engineering, University of Bologna, Viale Risorgimento 2, 40136 Bologna, Italy

^b TNO – TPD, Institute of Applied Physics, DOI – Division Optical Instrumentation, Stieltjesweg 1, 2600 AD Delft, The Netherlands

By kind information of the below cited authors of the present errata, the following two errors have been found:

- (1) In Section 4, end of first paragraph, the correct external load compatible with the results reported in the case study is $F_R = (-0.3, 0.0)$ N instead of $F_R = (-0.5, 0.0)$ N.
- (2) In Section 4.2, the correct expression for the angle θ_3 is $\theta_3 = -(\gamma - \gamma_0 - \beta + \beta_0)$ instead of $\theta_3 = \gamma - \gamma_0 - \beta + \beta_0$.

The authors of the original paper thank the commentators for their detailed analysis and for kindly conveying this information both to them and to the readers of this journal.

Authors of the errata:

Jorge E. Correa, Oscar E. Ruiz, Sebastián Durango

Laboratory of CAD CAM CAE, EAFIT University, Cra. 49 No. 7-sur-50, Medellín, Colombia.

Tel.: +57 4 261 9500x9521, 9382.

E-mail addresses: jcorre20@eafit.edu.co; oruiz@eafit.edu.co; sdurang1@eafit.edu.co

DOI of original article: [10.1016/j.mechmachtheory.2005.01.009](https://doi.org/10.1016/j.mechmachtheory.2005.01.009)

* Corresponding author.